

Predictive Maintenance Approaches and Goals

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01

10+ → 4

Approaches of PdM

PdM approaches from 10+ Scopus Q1 Articles:

There are at least **10** PdM approaches
(next slide).

There are **4** main approaches, i.e.:

- A. knowledge-based models,
- B. physical models,
- * C. data-driven models, and
- D. hybrid models

* the most often used currently.

| Authors, Year | PdM approaches |
|--------------------------|--|
| (Florian et al., 2021) | data driven |
| (Pech et al., 2021) | data-driven model/approach (the most often use in the current development of PdM), experience-driven, physical model (mathematical modeling), knowledge-based model (reduces the complexity of the physical model) |
| (Arena et al., 2022) | data-driven, model-driven, hybrid |
| (Vrignat et al., 2022) | data-driven, hybrid |
| (Javed et al., 2017) | data-driven, physic based |
| (Olesen & Shaker, 2020)) | data driven, physical model-based, knowledge-based, hybrid |
| (Zonta et al., 2020) | data-driven, physical model-based, knowledge-based, hybrid |
| (Bousdekis et al., 2018) | data-driven, knowledge- based on prognosis, model-based prognosis |
| (Davari et al., 2021) | data-driven prognosis |
| (Molęda et al., 2023) | data-driven, physics of failure, knowledge-based, model-based, signal based, qualitative, quantitative model, ML, statistical and stochastic methods |
| (Vogl et al., 2019) | Data-driven, hybrid/fusion, physics-based modelling = physics-based prognostic = physic model approach, physics-of-failure-based (PoF-based) methods |

A. PdM approach: knowledge-based models

*** approaches that reduce the complexity of a physical model.**

*** often used as a hybrid strategy (Ayad et al., 2018; Wu et al., 2016):**

- 1. expert systems, or**
- 2. fuzzy logic**

B. PdM approach: physical models-based

#main feature is mathematical modeling with reflexes the condition of a component

#needing the precision of the condition and measurement of failure, and statistical methods to limit these indices (Wu et al., 2017c)

C. PdM approach: data-driven models

#Approach based on **data** without prior knowledge of degradation conditions (Davari et al., 2021).

#3 Fase mengimplementasikan:

1. Mendefinisikan model operasional dari komponen/sistem yang dianalisis & mode kegagalan dari komponen/sistem untuk menetapkan tujuan dari PdM (Jardine et al., 2006; Accorsi et al., 2017).

PdM approach: data-driven models

- 2. Collect and manipulate the data (data selection, analysis, processing, modeling and evaluation for testing the feasibility of the predictive model).**
- 3. The implementation of a DSS (decision support system) support the most proper maintenance action (Bousdekis, et al., 2018)**

Data-driven: models most found in the current evolution of PdM solutions are statistics-based, pattern recognition, or artificial intelligence(AI) and models based on machine learning algorithms (Zonta et al., 2020).

D. PdM approach: hybrid models

#often used as a combination of several defined methods / approaches.

#Egs. (Zonta, et al., 2020;):

- Cloud-based
- Deep learning-based
- IoT-based
- Fleet-based
- Time-based*

| Penulis, Tahun | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|------------------------|---|------------------|---|--|-----------------------|--------------|--------------|---------------------------------|----|------------------------------------|
| Florian dkk. (2021) | data driven | | | | | | | | | |
| Pech et al., (2021) | data-driven model/approach (the most often use in the current development of PdM) | experiece-driven | physical model (mathematical modelling) | knowledge-based model (reduces the complexity of the physical model) | | | | | | |
| Arena dkk. (2022) | data-driven | | | | model-driven | hybrid | | | | |
| Vrignat dkk. (2022) | data-driven | | | | | hybrid | | | | |
| Javed et al., (2017) | data-driven | | physics based | | | | | | | |
| Olesen & Shaker (2020) | data driven | | physical-based model | knowledge-based model | | hybrid model | | | | |
| Zonta dkk. (2020) | data-driven | | Physical model-based | knowledge-based | | hybrid | | | | |
| Bousdekis dkk., (2018) | data-driven | | | knowledge-based prognosis | model-based prognosis | | | | | |
| Davari dkk., (2021) | data-driven prognosis | | | | | | | | | |
| Moleda dkk., (2023) | data-driven | | Physics of failure | knowledge-based | model-based | | signal-based | qualitative, quantitative model | ML | statistical and stochastic methods |
| | 10 | 1 | 5 | 5 | 3 | 4 | 1 | 1 | 1 | 1 |

02

20+ → 2

Goals of
PdM

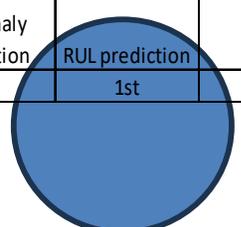
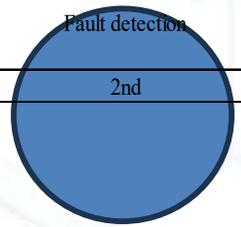
20+ → 2

Goals of PdM

It was found that there are 20+ PdM goals in the literatures surveyed.

The first two of the PdM goals: **RUL prediction followed by failure prediction.**

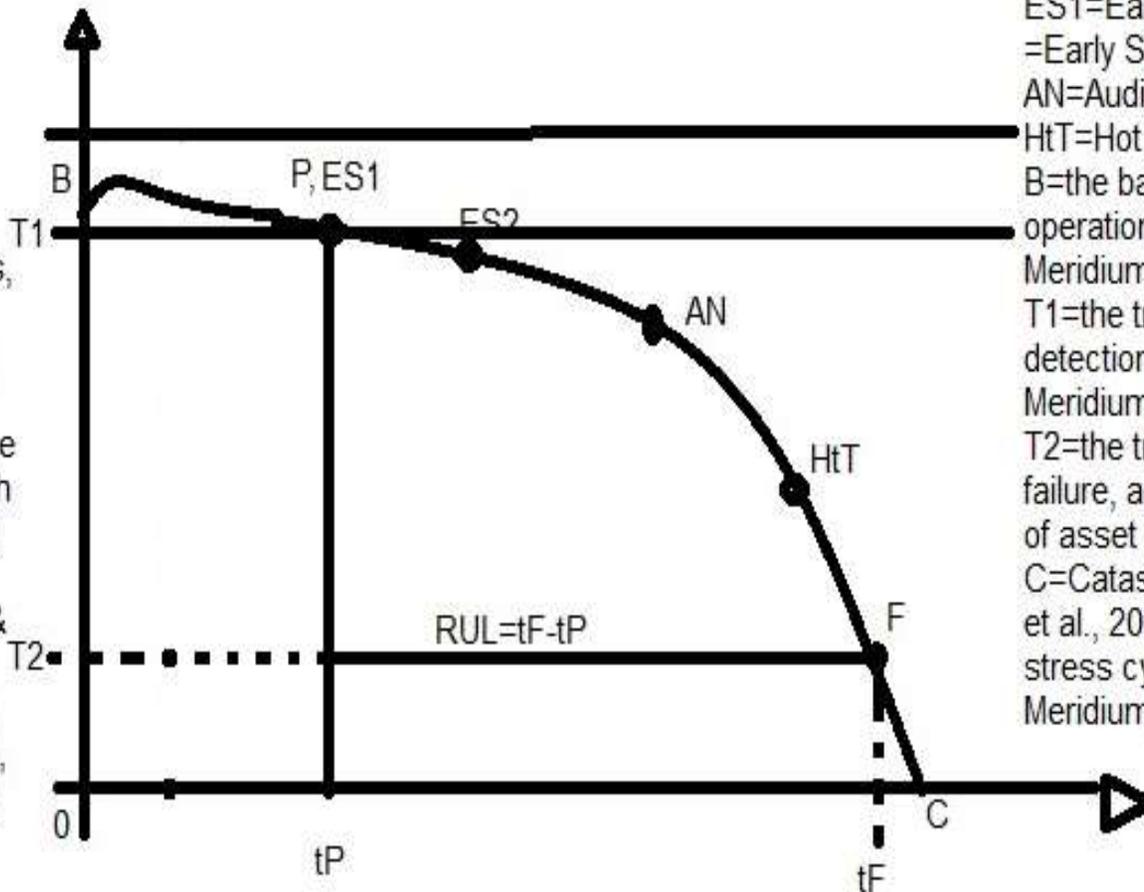
| Penulis, Tahun | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 |
|------------------------|--|---|------------------|-----------|----------------------|----------------|-----------------------|---------------------------------|----------------------|----------|-------------------------|-----------------|---------------------|
| Florian dkk. (2021) | | define whether the data sample in the time-series signals the occurrence of a failure or not. | | | | | | | | | | | |
| Pech et al., (2021) | failure prediction | health status | alarm | | anomaly | RUL | | | | | | | |
| Arena dkk. (2022) | faults diagnosis | | | prognosis | | RUL estimation | | | | | | | |
| Vrignat dkk. (2022) | | | | | | RUL prediction | efficient maintenance | | | | | | |
| Javed et al., (2017) | | | | | | RUL prediction | | | | | | | |
| Olesen & Shaker (2020) | failure prediction | health status | false/true alarm | | detection of anomaly | RUL | | degradation pattern prognostics | | | | | |
| Zonta dkk. (2020) | | | | | | | | | improve productivity | downtime | reduce maintenance cost | improve quality | |
| Bousdekis dkk., (2018) | > 20 goals/outputs pairs with inputs including: estimation of RUL, failure prediction, TTF, optimal maintenance policy, reliability , etc. | | | | | | | | | | | | |
| Davari dkk., (2021) | failure prediction | | | | | RUL prediction | | | | | | | |
| Moleda dkk., (2023) | Fault detection | Fault classification | | | Anomaly detection | RUL prediction | | | | | | | Root cause analysis |



RUL prediction: P-F Diagram

P-F Diagram

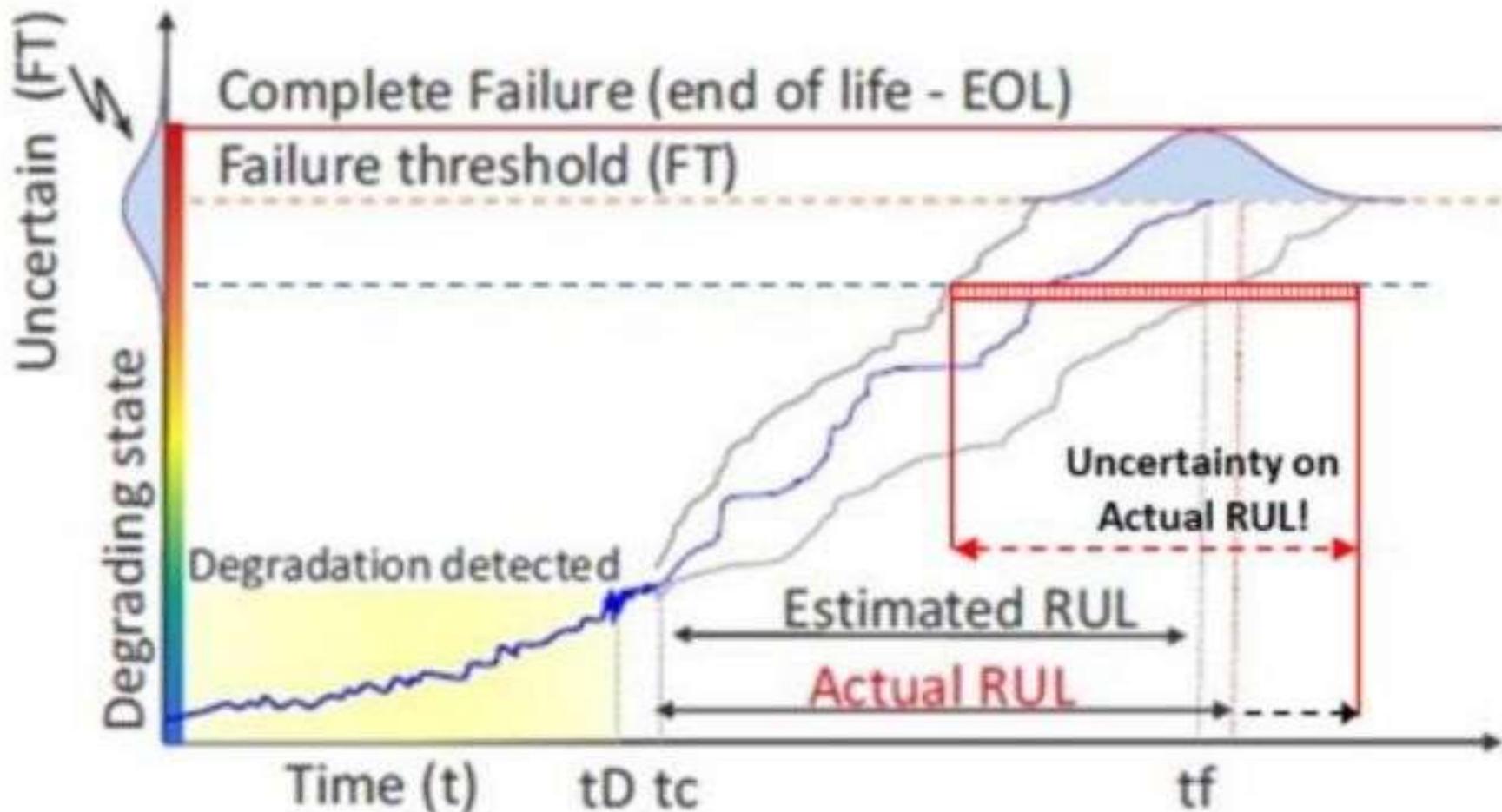
Sumbu Y:
 Performance
 (Jennions, 2018;
 Meridium, 2014;
 Davis, 2021) atau
 Condition (Jennions,
 2018; Meridium,
 2014; Davis, 2021;
 Moubrey, 1997)) or
 Resistance to failure
 atau machine health
 (MathWorks, 2019)
 or Equipment
 condition (Nowlan &
 Heap, 1978) or
 Component Health
 Index (Xiongzi et al.,
 2011) or Degrading
 State (ForeSen,
 2021)



ES1=Early Signal 1, ES2
 =Early Signal 2, (Nowlan
 AN=Audible Noise & Heap,
 HtT=Hot to Touch 1978
 B=the band of normal
 operation (Jennions, 2018;
 Meridium, 2014; Davis, 2021)
 T_1 =the treshold of
 detection/diagnosis (Jennions,
 Meridium, Davis)
 T_2 =the treshold of function
 failure, acceptable health level
 of asset (Xiongzi et al., 2011)
 C=Catastrohic Failure (Xiongzi
 et al., 2011), operating time or
 stress cycle (Jennions, 2018;
 Meridium, 2014; Davis, 2021)

Sumbu X:
 Waktu

Estimated RUL with uncertainty: P-F diagram (ForeSee, 2021;).



Fault / failure prediction

- Assessment of current equipment diagnostic conditions (sequence/data pattern) can be considered as the basis for fault/failure prediction.

03

References:
10+ **Scopus**
Quartile 1

References:

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